```
%                                Proakis & Salehi                          <Your Name>
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%
% 2.1.0  Plot the following signal
% x0(t) = rect((t - 1.875)/0.25) + u(t - 2)cos(2(pi)t)
%
% Note:  The code below calls m-files named "rect.m" and "u.m" but "cos" is built in.
  t_start =  -1
  t_stop  =  10;
  t_step  =   0.001;
  x_min   =  -1.2;
  x_max   =   1.2;

  eps = 0.0001;  % A small number used to prevent overlap at one sample point.
  t  = [t_start : t_step : t_stop];
  x0 = rect((t - 1.875)/0.25) + u(t - 2 - eps).*cos(2*pi*t);  % .* is element-by-element mult.
                                                   % wherease * is matrix multiplication
  plot (t, x0, 'k');                               % 'k' plots with a black line
  xlabel('t, (sec)');
  ylabel('x0(t), (volts)');
  title('x0(t) vs. t');
  axis([t_start, t_stop, x_min, x_max]);
```